Project Type	Agency	Project Name	Project Description
2020 Call for Applications			
Smart Cities & Mobility Innovations: 8 projects total; 5 contracts			
Curb Space	Los Angles Dept. of Transportation	Curb Zone Data Inventory for Digital Curb Management	A digital curb zone inventory to optimize commercial loading activities and advance digital stewardship.
	City of Long Beach	Long Beach Curb Space Management Study	A curb occupancy and usage study with real-time data collection and monitoring, focusing on underserved communities.
	City of Stanton	Stanton Citywide Curb Management Plan	An inventory to collect data in residential, commercial, and industrial neighborhoods and developing a Citywide Curb Management Plan to improve safety and quality of life.
Technology	San Gabriel Valley Council of Govts	GoSGV Engagement & Evaluation	Analysis of the GoSGV Regional E-Bike Share Program to quantify vehicle miles traveled (VMT) reductions and implement innovative outreach solutions with Community Based Organizations (CBOs).
Parking	City of Desert Hot Springs	Downtown and Light Industrial Parking Plan	A parking plan encompassing the commercial and light industrial hubs of the city along with a framework of innovative practices to meet future development and mobility demand needs.
	City of Garden Grove	Garden Grove Curb Data Study	Policies and actions for curb and parking management in several Environmental Justice areas to mitigate the disproportionate negative environmental impacts from parking.
Technology	City of Laguna Woods	Laguna Woods Mobility Technology Plan	A Mobility Technology Plan to establish new mobility service capabilities, particularly for senior and disabled populations, and the prospective future implementation of autonomous vehicle technology.
Technology	City of Rialto	Smart Cities Plan for Warehousing & Logistics	A Smart Cities Plan focused on the local impacts of warehousing and logistics and technological and policy solutions that could address those adverse impacts while supporting economic goals.